

### FEATURES

- Single **AD8041** and quad **AD8044** also available
- Fully specified at +3 V, +5 V, and  $\pm 5$  V supplies
- Output swings to within 30 mV of either rail
- Input voltage range extends 200 mV below ground
- No phase reversal with inputs 0.5 V beyond supplies
- Low power of 5.2 mA per amplifier
- High speed and fast settling on 5 V
  - 160 MHz, -3 dB bandwidth ( $G = +1$ )
  - 200 V/ $\mu$ s slew rate
  - 39 ns settling time to 0.1%
- Good video specifications ( $R_L = 150 \Omega$ ,  $G = +2$ )
  - Gain flatness of 0.1 dB to 14 MHz
  - 0.02% differential gain error
  - 0.04° differential phase error
- Low distortion: -64 dBc worst harmonic @ 10 MHz
- Drives 50 mA 0.5 V from supply rails

### APPLICATIONS

- Video switchers
- Distribution amplifiers
- Analog-to-digital drivers
- Professional cameras
- CCD Imaging systems
- Ultrasound equipment (multichannel)

### GENERAL DESCRIPTION

The AD8042 is a low power voltage feedback, high speed amplifier designed to operate on +3 V, +5 V, or  $\pm 5$  V supplies. It has true single-supply capability with an input voltage range extending 200 mV below the negative rail and within 1 V of the positive rail.

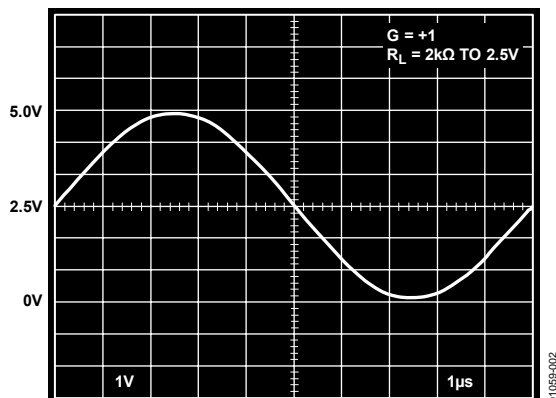


Figure 1. Output Swing: Gain = +1,  $V_S = +5$  V

### CONNECTION DIAGRAM

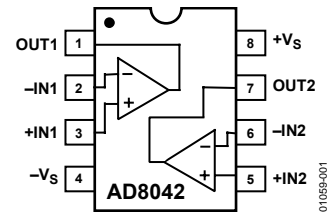


Figure 2. 8-Lead PDIP and 8-Lead SOIC\_N

The output voltage swing extends to within 30 mV of each rail, providing the maximum output dynamic range. Additionally, it features gain flatness of 0.1 dB to 14 MHz while offering differential gain and phase error of 0.04% and 0.06° on a single 5 V supply. This combination of features makes the AD8042 useful for professional video electronics, such as cameras, video switchers, or any high speed portable equipment. The low distortion and fast settling of the AD8042 make it ideal for buffering single-supply, high speed analog-to-digital converters (ADCs).

The AD8042 offers a low power supply current of 12 mA maximum and can run on a single 3.3 V power supply. These features are ideally suited for portable and battery-powered applications where size and power are critical.

The wide bandwidth of 160 MHz along with 200 V/ $\mu$ s of slew rate on a single 5 V supply make the AD8042 useful in many general-purpose, high speed applications where single supplies from +3.3 V to +12 V and dual power supplies of up to  $\pm 6$  V are needed. The AD8042 is available in 8-lead PDIP and 8-lead SOIC\_N packages.

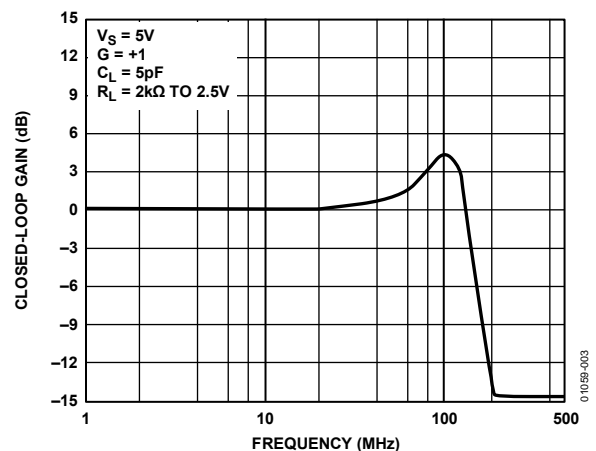


Figure 3. Frequency Response

#### Rev. E

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**REVISION HISTORY**

**12/07—Rev. D to Rev. E**

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**3/06—Rev. C to Rev. D**

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**8/04—Rev. B to Rev. C**

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**7/02—Rev. A to Rev. B**

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## SPECIFICATIONS

$T_A = 25^\circ\text{C}$ ,  $V_S = 5\text{ V}$ ,  $R_L = 2\text{ k}\Omega$  to  $2.5\text{ V}$ , unless otherwise noted.

**Table 1.**

Parameter	Conditions	Min	Typ	Max	Unit
<b>DYNAMIC PERFORMANCE</b>					
-3 dB Small Signal Bandwidth, $V_O < 0.5\text{ V p-p}$	$G = +1$	125	160		MHz
Bandwidth for 0.1 dB Flatness	$G = +2$ , $R_L = 150\ \Omega$ , $R_F = 200\ \Omega$		14		MHz
Slew Rate	$G = -1$ , $V_{OUT} = 2\text{ V step}$	130	200		$\text{V}/\mu\text{s}$
Full Power Response	$V_O = 2\text{ V p-p}$		30		MHz
Settling Time to 1%	$G = -1$ , $V_{OUT} = 2\text{ V step}$		26		ns
Settling Time to 0.1%			39		ns
<b>NOISE/DISTORTION PERFORMANCE</b>					
Total Harmonic Distortion	$f_C = 5\text{ MHz}$ , $V_{OUT} = 2\text{ V p-p}$ , $G = +2$ , $R_L = 1\text{ k}\Omega$		-73		dB
Input Voltage Noise	$f = 10\text{ kHz}$		15		$\text{nV}/\sqrt{\text{Hz}}$
Input Current Noise	$f = 10\text{ kHz}$		700		$\text{fA}/\sqrt{\text{Hz}}$
Differential Gain Error (NTSC, 100 IRE)	$G = +2$ , $R_L = 150\ \Omega$ to $2.5\text{ V}$		0.04	0.06	%
	$G = +2$ , $R_L = 75\ \Omega$ to $2.5\text{ V}$		0.04		%
Differential Phase Error (NTSC, 100 IRE)	$G = +2$ , $R_L = 150\ \Omega$ to $2.5\text{ V}$		0.06	0.12	Degrees
	$G = +2$ , $R_L = 75\ \Omega$ to $2.5\text{ V}$		0.24		Degrees
Worst-Case Crosstalk	$f = 5\text{ MHz}$ , $R_L = 150\ \Omega$ to $2.5\text{ V}$		-63		dB
<b>DC PERFORMANCE</b>					
Input Offset Voltage			3	9	mV
	$T_{MIN}$ to $T_{MAX}$			12	mV
Offset Drift			12		$\mu\text{V}/^\circ\text{C}$
Input Bias Current			1.2	3.2	$\mu\text{A}$
	$T_{MIN}$ to $T_{MAX}$			4.8	$\mu\text{A}$
Input Offset Current			0.2	0.5	$\mu\text{A}$
Open-Loop Gain	$R_L = 1\text{ k}\Omega$	90	100		dB
	$T_{MIN}$ to $T_{MAX}$		90		dB
<b>INPUT CHARACTERISTICS</b>					
Input Resistance			300		k $\Omega$
Input Capacitance			1.5		pF
Input Common-Mode Voltage Range			-0.2 to +4		V
Common-Mode Rejection Ratio	$V_{CM} = 0\text{ V}$ to $3.5\text{ V}$	68	74		dB
<b>OUTPUT CHARACTERISTICS</b>					
Output Voltage Swing	$R_L = 10\text{ k}\Omega$ to $2.5\text{ V}$		0.03 to 4.97		V
	$R_L = 1\text{ k}\Omega$ to $2.5\text{ V}$	0.10 to 4.9	0.05 to 4.95		V
	$R_L = 50\ \Omega$ to $2.5\text{ V}$	0.4 to 4.4	0.36 to 4.45		V
Output Current	$T_{MIN}$ to $T_{MAX}$ , $V_{OUT} = 0.5\text{ V}$ to $4.5\text{ V}$		50		mA
Short-Circuit Current	Sourcing		90		mA
	Sinking		100		mA
Capacitive Load Drive	$G = +1$		20		pF
<b>POWER SUPPLY</b>					
Operating Range		3		12	V
Quiescent Current (Per Amplifier)			5.5	6.4	mA
Power Supply Rejection Ratio	$V_{S-} = 0\text{ V}$ to $-1\text{ V}$ , or $V_{S+} = 5\text{ V}$ to $6\text{ V}$	72	80		dB
<b>OPERATING TEMPERATURE RANGE</b>					
		-40		+85	$^\circ\text{C}$

# AD8042

$T_A = 25^\circ\text{C}$ ,  $V_S = 3\text{ V}$ ,  $R_L = 2\text{ k}\Omega$  to  $1.5\text{ V}$ , unless otherwise noted.

**Table 2.**

Parameter	Conditions	Min	Typ	Max	Unit
<b>DYNAMIC PERFORMANCE</b>					
-3 dB Small Signal Bandwidth, $V_O < 0.5\text{ V p-p}$	$G = +1$	120	140		MHz
Bandwidth for 0.1 dB Flatness	$G = +2$ , $R_L = 150\ \Omega$ , $R_F = 200\ \Omega$		11		MHz
Slew Rate	$G = -1$ , $V_{OUT} = 2\text{ V step}$	120	170		V/ $\mu\text{s}$
Full Power Response	$V_O = 2\text{ V p-p}$		25		MHz
Settling Time to 1%	$G = -1$ , $V_{OUT} = 1\text{ V step}$		30		ns
Settling Time to 0.1%			45		ns
<b>NOISE/DISTORTION PERFORMANCE</b>					
Total Harmonic Distortion	$f_c = 5\text{ MHz}$ , $V_{OUT} = 2\text{ V p-p}$ , $G = -1$ , $R_L = 100\ \Omega$		-56		dB
Input Voltage Noise	$f = 10\text{ kHz}$		16		nV/ $\sqrt{\text{Hz}}$
Input Current Noise	$f = 10\text{ kHz}$		500		fA/ $\sqrt{\text{Hz}}$
Differential Gain Error (NTSC, 100 IRE)	$G = +2$ , $R_L = 150\ \Omega$ to $1.5\text{ V}$ , Input $V_{CM} = 1\text{ V}$		0.10		%
	$R_L = 75\ \Omega$ to $1.5\text{ V}$ , Input $V_{CM} = 1\text{ V}$		0.10		%
Differential Phase Error (NTSC, 100 IRE)	$G = +2$ , $R_L = 150\ \Omega$ to $1.5\text{ V}$ , Input $V_{CM} = 1\text{ V}$		0.12		Degrees
	$R_L = 75\ \Omega$ to $1.5\text{ V}$ , Input $V_{CM} = 1\text{ V}$		0.27		Degrees
Worst-Case Crosstalk	$f = 5\text{ MHz}$ , $R_L = 1\text{ k}\Omega$ to $1.5\text{ V}$		-68		dB
<b>DC PERFORMANCE</b>					
Input Offset Voltage			3	9	mV
	$T_{MIN}$ to $T_{MAX}$			12	mV
Offset Drift			12		$\mu\text{V}/^\circ\text{C}$
Input Bias Current			1.2	3.2	$\mu\text{A}$
	$T_{MIN}$ to $T_{MAX}$			4.8	$\mu\text{A}$
Input Offset Current			0.2	0.6	$\mu\text{A}$
Open-Loop Gain	$R_L = 1\text{ k}\Omega$	90	100		dB
	$T_{MIN}$ to $T_{MAX}$		90		dB
<b>INPUT CHARACTERISTICS</b>					
Input Resistance			300		k $\Omega$
Input Capacitance			1.5		pF
Input Common-Mode Voltage Range			-0.2 to +2		V
Common-Mode Rejection Ratio	$V_{CM} = 0\text{ V}$ to $1.5\text{ V}$	66	74		dB
<b>OUTPUT CHARACTERISTICS</b>					
Output Voltage Swing	$R_L = 10\text{ k}\Omega$ to $1.5\text{ V}$		0.03 to 2.97		V
	$R_L = 1\text{ k}\Omega$ to $1.5\text{ V}$	0.1 to 2.9	0.05 to 2.95		V
	$R_L = 50\ \Omega$ to $1.5\text{ V}$	0.3 to 2.6	0.25 to 2.65		V
Output Current	$T_{MIN}$ to $T_{MAX}$ , $V_{OUT} = 0.5\text{ V}$ to $2.5\text{ V}$		50		mA
Short-Circuit Current	Sourcing		50		mA
	Sinking		70		mA
Capacitive Load Drive	$G = +1$		17		pF
<b>POWER SUPPLY</b>					
Operating Range		3		12	V
Quiescent Current (Per Amplifier)			5.5	6.4	mA
Power Supply Rejection Ratio	$V_{S-} = 0\text{ V}$ to $-1\text{ V}$ , or $V_{S+} = 3\text{ V}$ to $4\text{ V}$	68	80		dB
<b>OPERATING TEMPERATURE RANGE</b>					
		0		70	$^\circ\text{C}$

$T_A = 25^\circ\text{C}$ ,  $V_S = \pm 5\text{ V}$ ,  $R_L = 2\text{ k}\Omega$  to  $0\text{ V}$ , unless otherwise noted.

**Table 3.**

Parameter	Conditions	Min	Typ	Max	Unit
<b>DYNAMIC PERFORMANCE</b>					
-3 dB Small Signal Bandwidth, $V_O < 0.5\text{ V p-p}$	$G = +1$	125	170		MHz
Bandwidth for 0.1 dB Flatness	$G = +2$ , $R_L = 150\ \Omega$ , $R_F = 200\ \Omega$		18		MHz
Slew Rate	$G = -1$ , $V_{OUT} = 2\text{ V step}$	145	225		V/ $\mu\text{s}$
Full Power Response	$V_O = 2\text{ V p-p}$		35		MHz
Settling Time to 1%	$G = -1$ , $V_{OUT} = 2\text{ V step}$		22		ns
Settling Time to 0.1%			32		ns
<b>NOISE/DISTORTION PERFORMANCE</b>					
Total Harmonic Distortion	$f_c = 5\text{ MHz}$ , $V_O = 2\text{ V p-p}$ , $G = +2$ , $R_L = 1\text{ k}\Omega$		-78		dB
Input Voltage Noise	$f = 10\text{ kHz}$		15		nV/ $\sqrt{\text{Hz}}$
Input Current Noise	$f = 10\text{ kHz}$		700		fA/ $\sqrt{\text{Hz}}$
Differential Gain Error (NTSC, 100 IRE)	$G = +2$ , $R_L = 150\ \Omega$		0.02	0.05	%
	$G = +2$ , $R_L = 75\ \Omega$		0.02		%
Differential Phase Error (NTSC, 100 IRE)	$G = +2$ , $R_L = 150\ \Omega$		0.04	0.10	Degrees
	$G = +2$ , $R_L = 75\ \Omega$		0.12		Degrees
Worst-Case Crosstalk	$f = 5\text{ MHz}$ , $R_L = 150\ \Omega$		-63		dB
<b>DC PERFORMANCE</b>					
Input Offset Voltage			3	9.8	mV
	$T_{MIN}$ to $T_{MAX}$			14	mV
Offset Drift			12		$\mu\text{V}/^\circ\text{C}$
Input Bias Current			1.2	3.2	$\mu\text{A}$
	$T_{MIN}$ to $T_{MAX}$			4.8	$\mu\text{A}$
Input Offset Current			0.2	0.6	$\mu\text{A}$
Open-Loop Gain	$R_L = 1\text{ k}\Omega$	90	94		dB
	$T_{MIN}$ to $T_{MAX}$		86		dB
<b>INPUT CHARACTERISTICS</b>					
Input Resistance			300		k $\Omega$
Input Capacitance			1.5		pF
Input Common-Mode Voltage Range			-5.2 to +4		V
Common-Mode Rejection Ratio	$V_{CM} = -5\text{ V to } +3.5\text{ V}$	66	74		dB
<b>OUTPUT CHARACTERISTICS</b>					
Output Voltage Swing	$R_L = 10\text{ k}\Omega$		-4.97 to +4.97		V
	$R_L = 1\text{ k}\Omega$	-4.8 to +4.8	-4.9 to +4.9		V
	$R_L = 50\ \Omega$	-4 to +3.2	-4.2 to +3.5		V
Output Current	$T_{MIN}$ to $T_{MAX}$ , $V_{OUT} = -4.5\text{ V to } +4.5\text{ V}$		50		mA
Short-Circuit Current	Sourcing		100		mA
	Sinking		100		mA
Capacitive Load Drive	$G = +1$		25		pF
<b>POWER SUPPLY</b>					
Operating Range		3		12	V
Quiescent Current (Per Amplifier)			6	7	mA
Power Supply Rejection Ratio	$V_{S-} = -5\text{ V to } -6\text{ V}$ , or $V_{S+} = 5\text{ V to } 6\text{ V}$	68	80		dB
<b>OPERATING TEMPERATURE RANGE</b>					
		-40		+85	$^\circ\text{C}$

## ABSOLUTE MAXIMUM RATINGS

Table 4.

Parameter	Rating
Supply Voltage	12.6 V
Internal Power Dissipation <sup>1</sup>	
8-Lead PDIP (N)	1.3 W
8-Lead SOIC_N (R)	0.9 W
Input Voltage (Common Mode)	$\pm V_S \pm 0.5$ V
Differential Input Voltage	$\pm 3.4$ V
Output Short-Circuit Duration	Observe Power Derating Curves
Storage Temperature Range (N, R)	$-65^{\circ}\text{C}$ to $+125^{\circ}\text{C}$
Lead Temperature (Soldering, 10 sec)	$300^{\circ}\text{C}$

<sup>1</sup> Specification is for the device in free air:  
 8-Lead PDIP:  $\theta_{JA} = 90^{\circ}\text{C}/\text{W}$   
 8-Lead SOIC\_N:  $\theta_{JA} = 155^{\circ}\text{C}/\text{W}$ .

Stresses above those listed under Absolute Maximum Ratings may cause permanent damage to the device. This is a stress rating only; functional operation of the device at these or any other conditions above those indicated in the operational section of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

### MAXIMUM POWER DISSIPATION

The maximum power that can be safely dissipated by the AD8042 is limited by the associated rise in junction temperature. The maximum safe junction temperature for plastic encapsulated devices is determined by the glass transition temperature of the plastic, approximately  $150^{\circ}\text{C}$ . Exceeding this limit temporarily can cause a shift in parametric performance due to a change in the stresses exerted on the die by the package.

Exceeding a junction temperature of  $175^{\circ}\text{C}$  for an extended period can result in device failure.

While the AD8042 is internally short-circuit protected, this may not be sufficient to guarantee that the maximum junction temperature ( $150^{\circ}\text{C}$ ) is not exceeded under all conditions. To ensure proper operation, it is necessary to observe the maximum power derating curves.

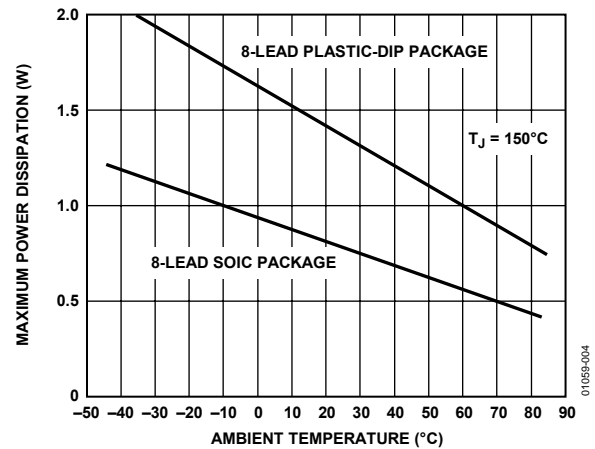


Figure 4. Maximum Power Dissipation vs. Temperature

### ESD CAUTION



**ESD (electrostatic discharge) sensitive device.** Charged devices and circuit boards can discharge without detection. Although this product features patented or proprietary protection circuitry, damage may occur on devices subjected to high energy ESD. Therefore, proper ESD precautions should be taken to avoid performance degradation or loss of functionality.

# TYPICAL PERFORMANCE CHARACTERISTICS

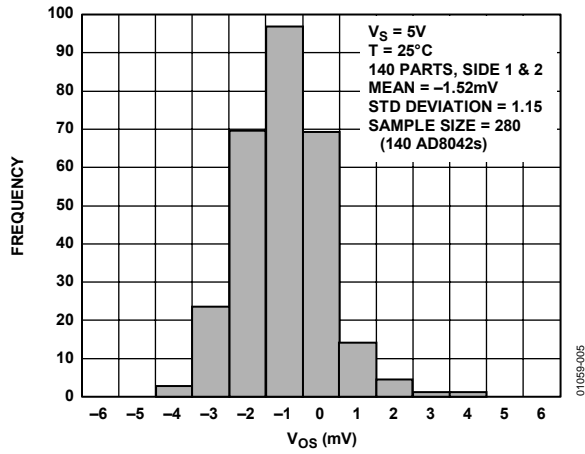


Figure 5. Typical Distribution of  $V_{OS}$

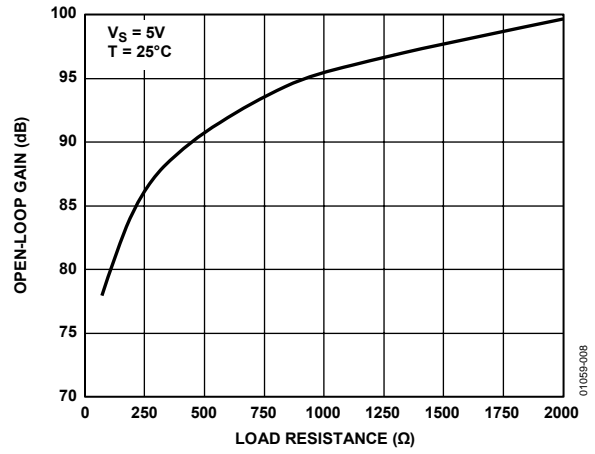


Figure 8. Open-Loop Gain vs.  $R_L$  to 2.5 V

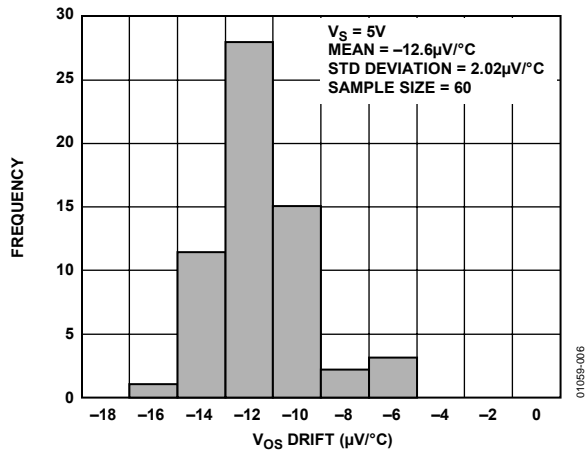


Figure 6.  $V_{OS}$  Drift Over  $-40^{\circ}\text{C}$  to  $+85^{\circ}\text{C}$

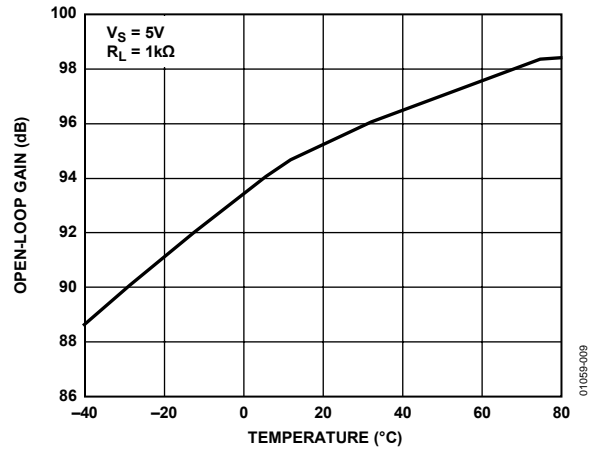


Figure 9. Open-Loop Gain vs. Temperature

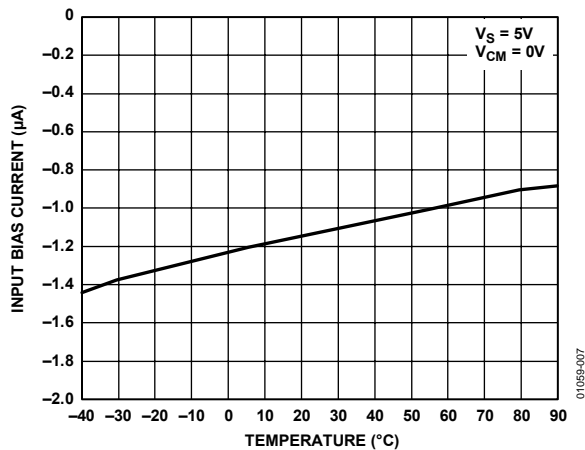


Figure 7.  $I_B$  vs. Temperature

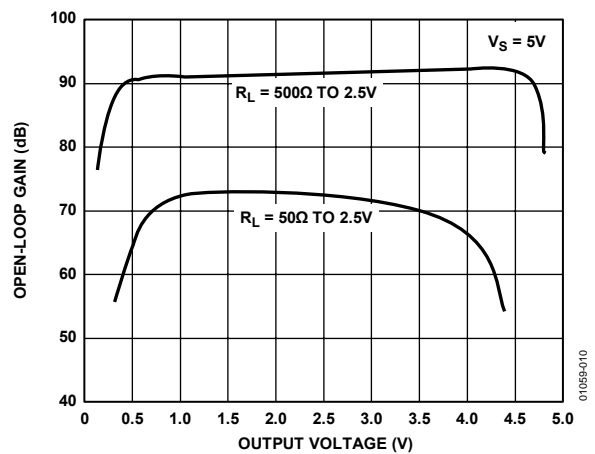


Figure 10. Open-Loop Gain vs. Output Voltage

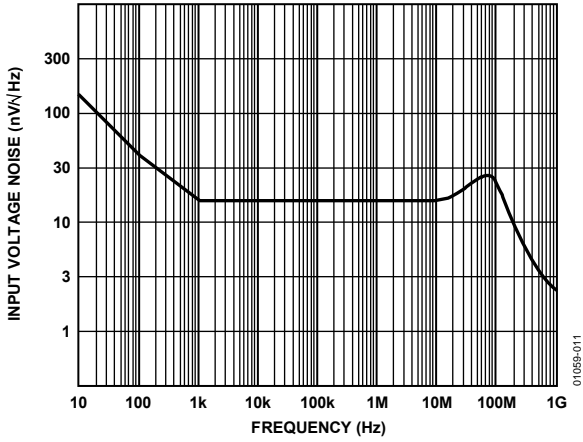


Figure 11. Input Voltage Noise vs. Frequency

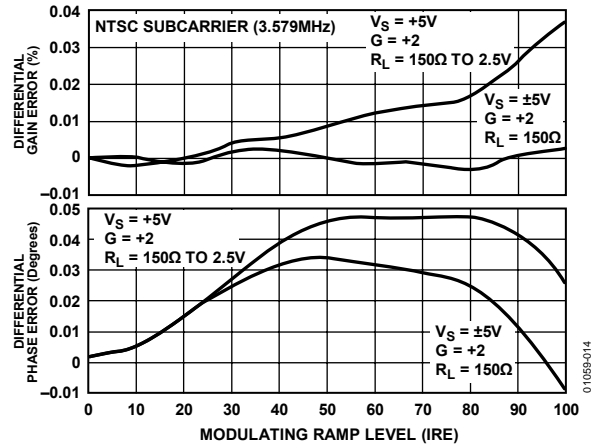


Figure 14. Differential Gain and Phase Errors

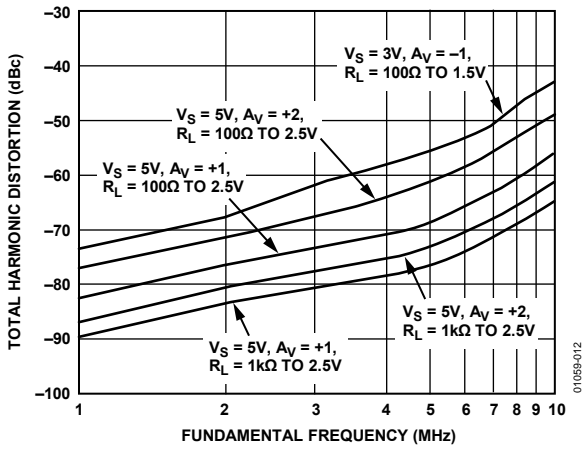


Figure 12. Total Harmonic Distortion vs. Frequency

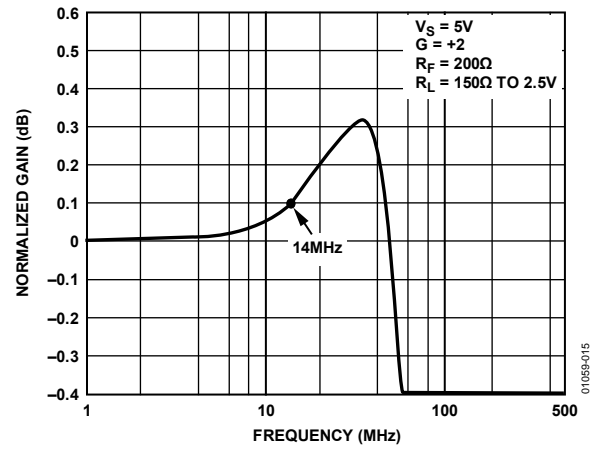


Figure 15. 0.1 dB Gain Flatness

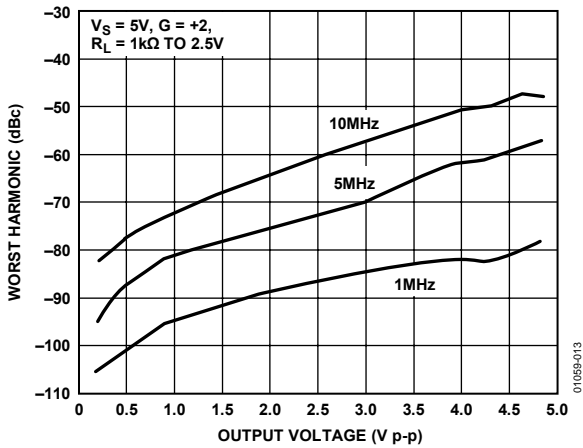


Figure 13. Worst Harmonic vs. Output Voltage

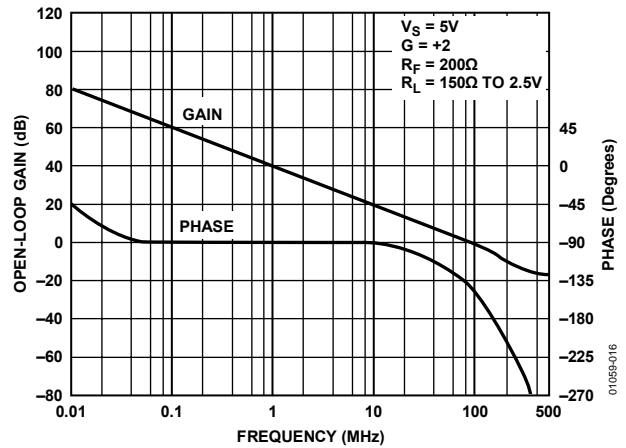


Figure 16. Open-Loop Gain and Phase vs. Frequency



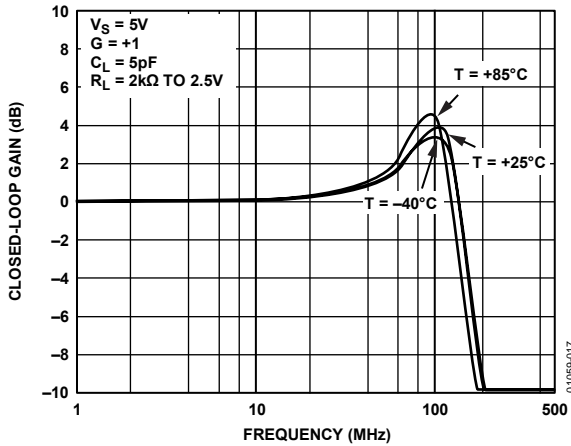


Figure 17. Closed-Loop Frequency Response vs. Temperature

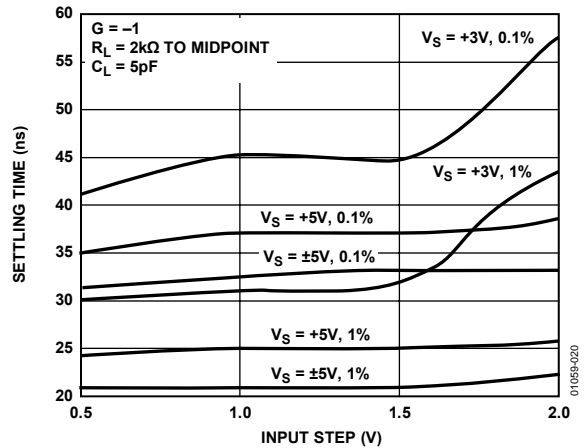


Figure 20. Settling Time vs. Input Voltage

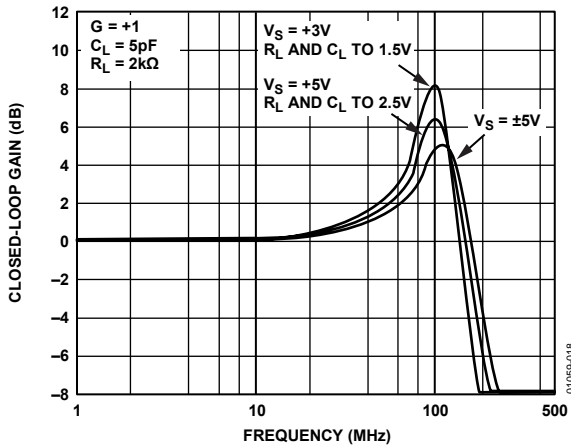


Figure 18. Closed-Loop Frequency Response vs. Supply

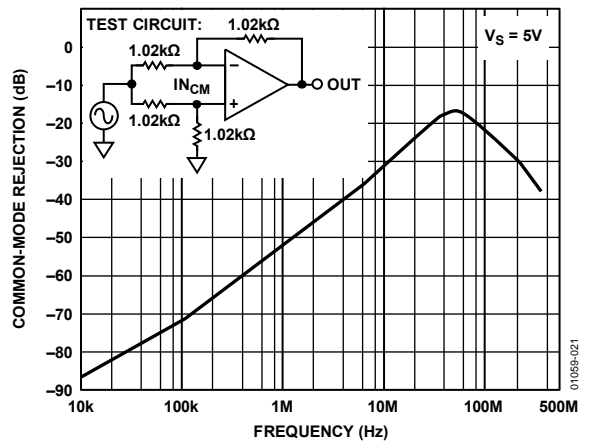


Figure 21. Common-Mode Rejection vs. Frequency

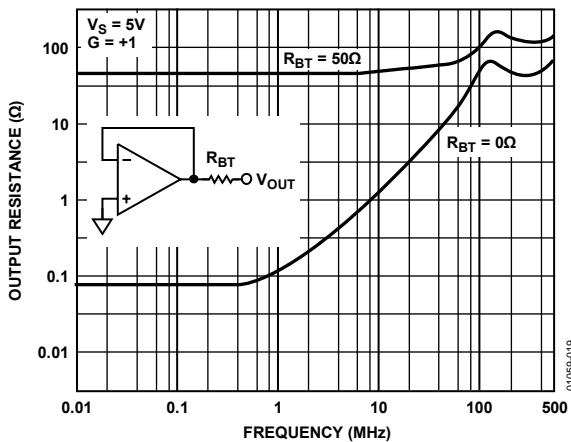


Figure 19. Output Resistance vs. Frequency

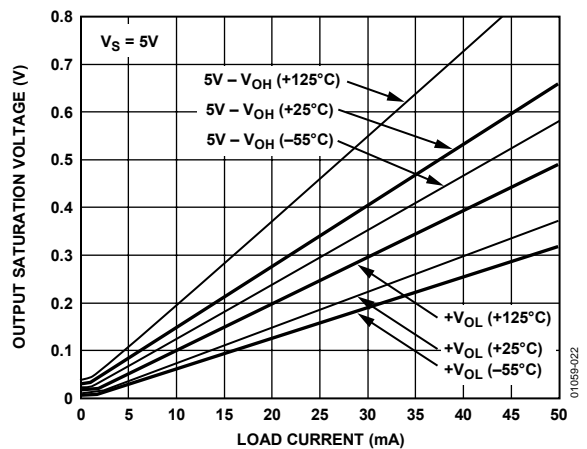


Figure 22. Output Saturation Voltage vs. Load Current

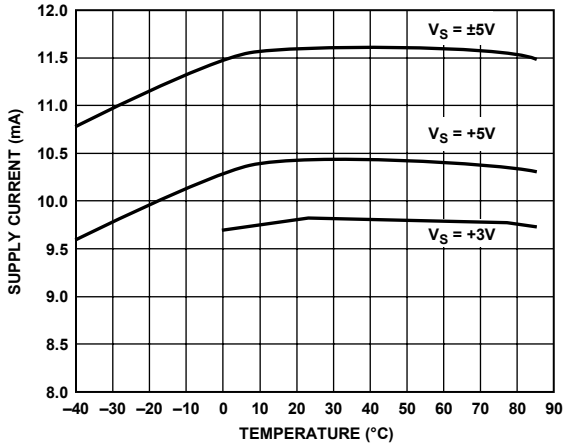


Figure 23. Supply Current vs. Temperature

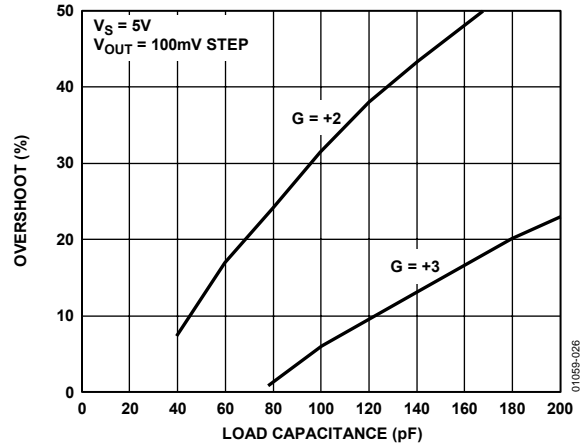


Figure 26. Overshoot vs. Load Capacitance

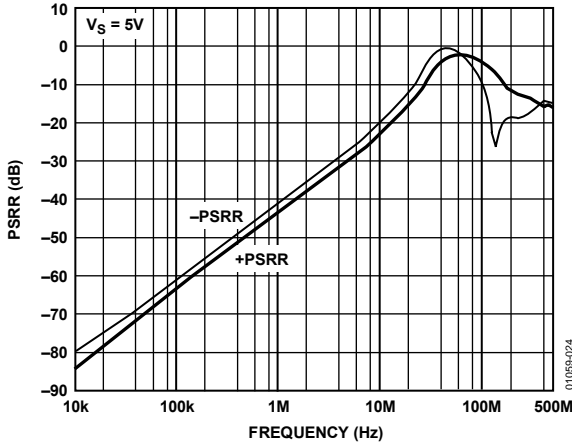


Figure 24. PSRR vs. Frequency

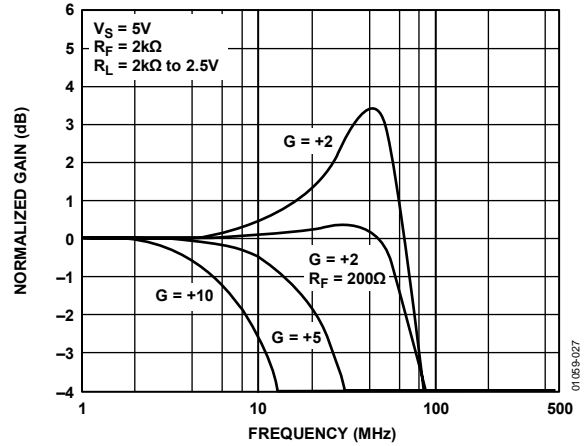


Figure 27. Closed-Loop Gain vs. Frequency Response

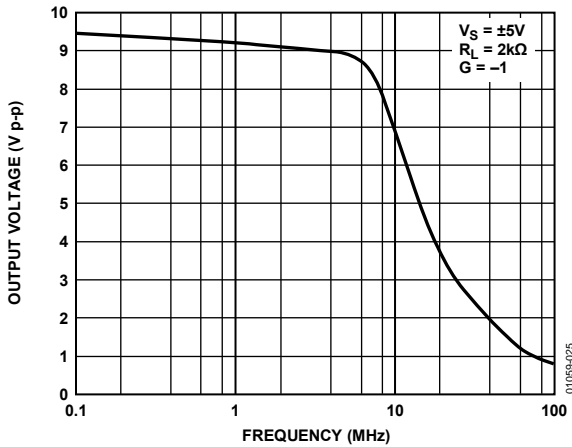


Figure 25. Output Voltage vs. Frequency

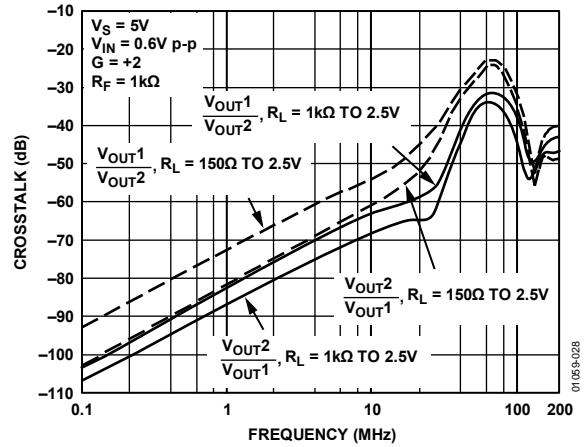


Figure 28. Crosstalk (Output-to-Output) vs. Frequency

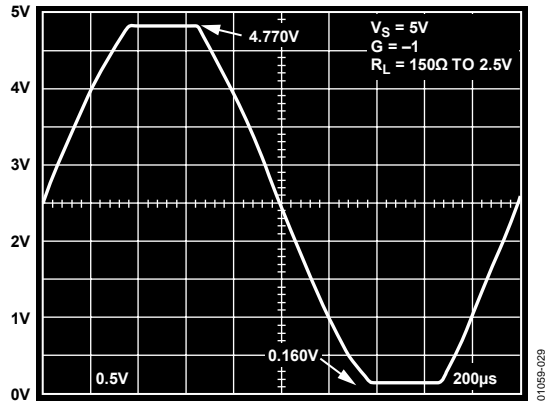


Figure 29. Output Swing with Load Reference to Supply Midpoint

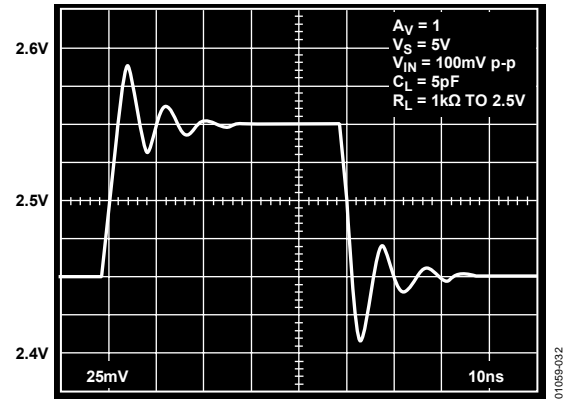


Figure 32. 100 mV Pulse Response,  $V_S = 5V$

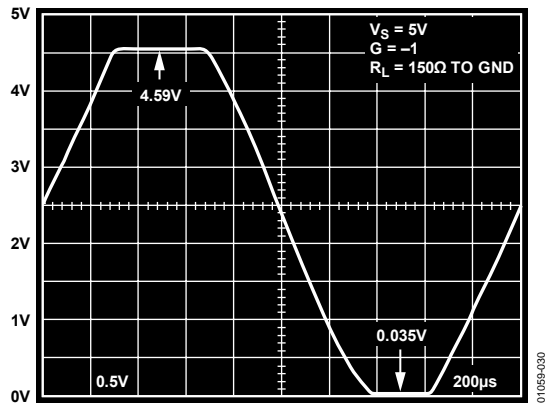


Figure 30. Output Swing with Load Reference to Negative to Supply

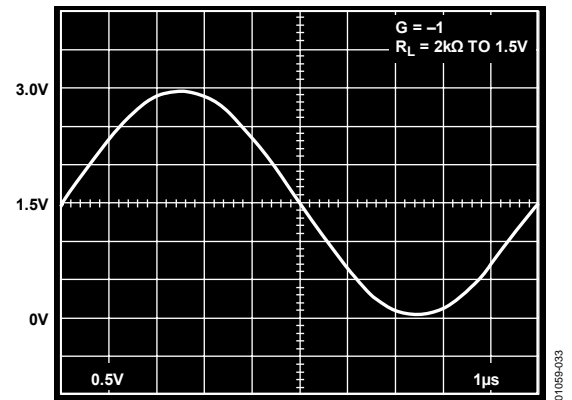


Figure 33. Rail-to-Rail Output Swing,  $V_S = 3V$

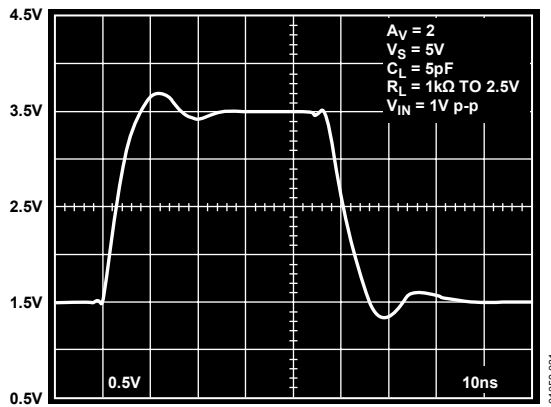


Figure 31. 1 V Pulse Response,  $V_S = 5V$

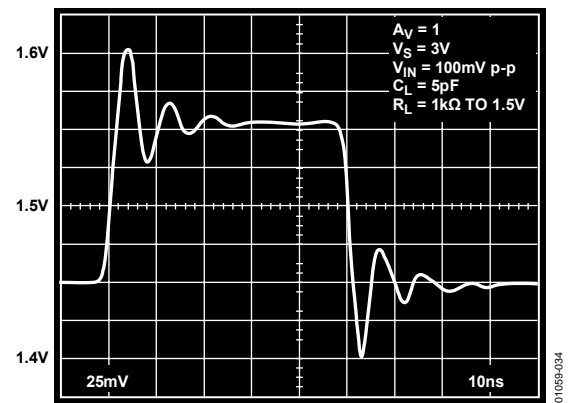


Figure 34. 100 mV Pulse Response,  $V_S = 3V$

## APPLICATIONS INFORMATION

### CIRCUIT DESCRIPTION

The AD8042 is fabricated on the Analog Devices, Inc., proprietary eXtra-Fast Complementary Bipolar (XFCB) process, which enables the construction of PNP and NPN transistors with similar  $f_s$  in the 2 GHz to 4 GHz region. The process is dielectrically isolated to eliminate the parasitic and latch-up problems caused by junction isolation. These features allow the construction of high frequency, low distortion amplifiers with low supply currents. This design uses a differential output input stage to maximize bandwidth and headroom (see Figure 35). The smaller signal swings required on the first stage outputs (nodes SIP, SIN) reduce the effect of nonlinear currents due to junction capacitances and improve the distortion performance. With this design, harmonic distortion of better than  $-77$  dB @ 1 MHz into  $100 \Omega$  with  $V_{OUT} = 2$  V p-p (gain = +2) on a single 5 V supply is achieved.

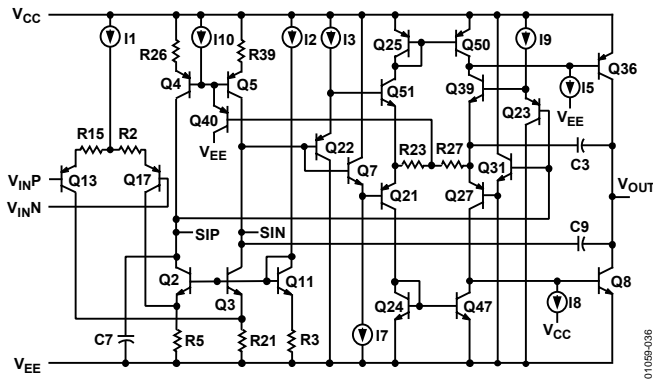


Figure 35. Simplified Schematic

The rail-to-rail output range of the AD8042 is provided by a complementary common-emitter output stage. High output drive capability is provided by injecting all output stage predriver currents directly into the bases of the output devices Q8 and Q36. Biasing of Q8 and Q36 is accomplished by I8 and I5, along with a common-mode feedback loop (not shown). This circuit topology allows the AD8042 to drive 40 mA of output current with the outputs within 0.5 V of the supply rails.

On the input side, the device can handle voltages from 0.2 V below the negative rail to within 1.2 V of the positive rail. Exceeding these values does not cause phase reversal; however, the input ESD devices do begin to conduct if the input voltages exceed the rails by greater than 0.5 V.

### DRIVING CAPACITIVE LOADS

The capacitive load drive of the AD8042 can be increased by adding a low valued resistor in series with the load. Figure 36 shows the effects of a series resistor on capacitive drive for varying voltage gains. As the closed-loop gain is increased, the larger phase margin allows for larger capacitive loads with less overshoot. Adding a series resistor with lower closed-loop gains accomplishes the same effect. For large capacitive loads, the frequency response of the amplifier is dominated by the roll-off of the series resistor and capacitive load.

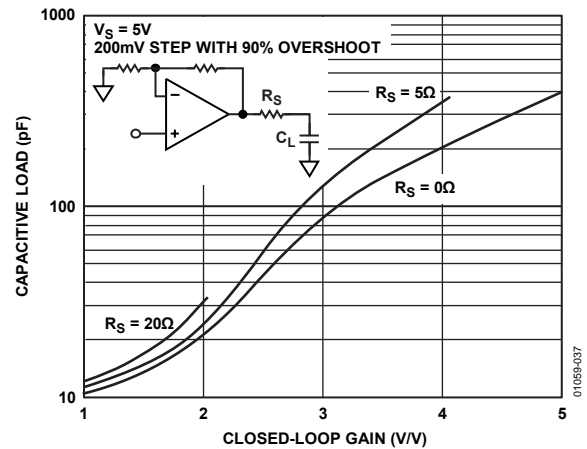


Figure 36. Capacitive Load Drive vs. Closed-Loop Gain

### OVERDRIVE RECOVERY

Overdrive of an amplifier occurs when the output and/or input range are exceeded. The amplifier must recover from this overdrive condition. As shown in Figure 37, the AD8042 recovers within 30 ns from negative overdrive and within 25 ns from positive overdrive.

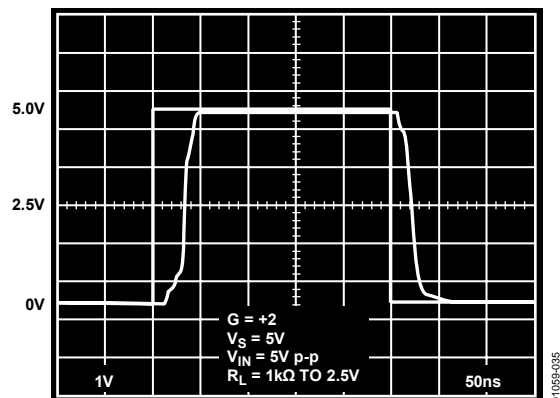


Figure 37. Overdrive Recovery



# AD8042

## Single-Ended-to-Differential Driver

Using a cross-coupled, single-ended-to-differential converter (SEDC), the AD8042 makes a good general-purpose differential line driver. This SEDC can be used for applications such as driving Category-5 (CAT-5) twisted pair wires. Figure 39 shows a configuration for a circuit that performs this function that can be used for video transmission over a differential pair or various data communication purposes.

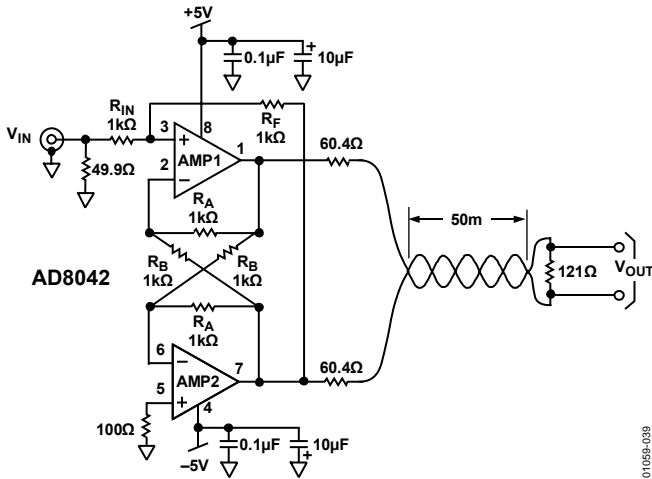


Figure 39. Single-Ended-to-Differential Twisted Pair Line Driver

Each of the op amps of the AD8042 is configured as a unity gain follower by the feedback resistors ( $R_A$ ). Each op amp output also drives the other as a unity gain inverter via  $R_B$ , creating a totally symmetrical circuit.

If the noninverting input of AMP2 is grounded and a small positive signal is applied to the noninverting input of AMP1, the output of AMP1 is driven to saturation in the positive direction and the input of AMP2 is driven to saturation in the negative direction. This is similar to the way a conventional op amp behaves without any feedback.

If a resistor ( $R_F$ ) is connected from the output of AMP2 to the noninverting input of AMP1, negative feedback is provided, which closes the loop. An input resistor ( $R_{IN}$ ) makes the circuit look like a conventional inverting op amp configuration with differential outputs.

The gain of this circuit from input to either output is  $\pm R_F/R_{IN}$ , or the single-ended-to-differential gain is  $2 \times R_F/R_{IN}$ . This gives the circuit the advantage of being able to adjust its gain by changing a single resistor.

The cable has a characteristic impedance of about  $120 \Omega$ . Each driver output is back terminated with a pair of  $60.4 \Omega$  resistors to make the source look like  $120 \Omega$ . The receive end is terminated with  $121 \Omega$ , and the signal is measured differentially with a pair of scope probes. One channel on the oscilloscope is inverted and then the signals are added.

Figure 40 shows the results of the circuit in Figure 39 driving 50 meters of CAT-5 cable.

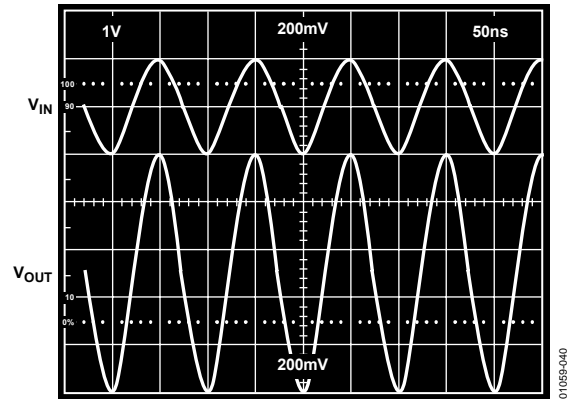


Figure 40. Differential Driver Frequency Response

## Single-Supply Differential A/D Driver

The single-ended-to-differential converter circuit is also useful as a differential driver for video speed, single-ended, differential input ADCs. Figure 41 is a schematic that shows such a circuit differentially driving an AD9220, a 12-bit, 10 MSPS ADC.

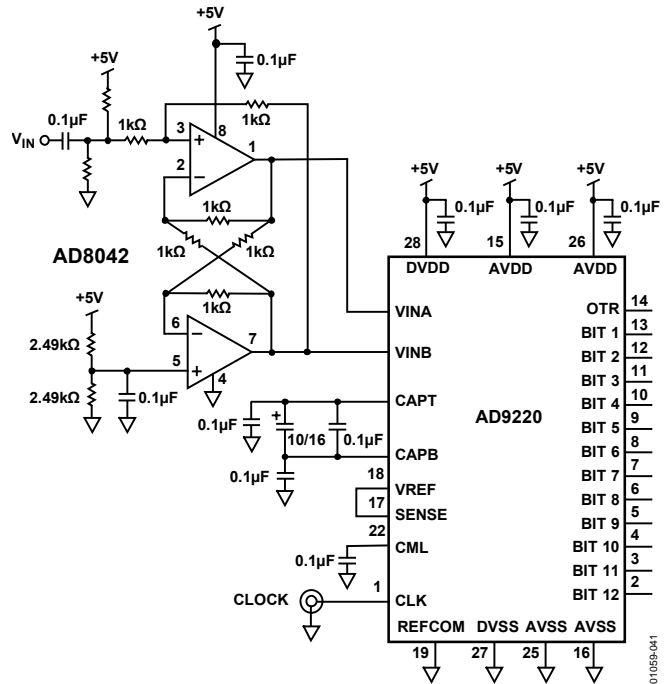


Figure 41. AD8042 Differential Driver for the AD9220 12-Bit, 10 MSPS ADC

The circuit was tested with a 1 MHz input signal and clocked at 10 MHz. An FFT response of the digital output is shown in Figure 42.

Pin 5 is biased at 2.5 V by the voltage divider and bypassed. This biases each output at 2.5 V.  $V_{IN}$  is ac-coupled such that  $V_{IN}$  going positive makes  $V_{INA}$  go positive and  $V_{INB}$  go in the negative direction. The opposite happens for a negative going  $V_{IN}$ .

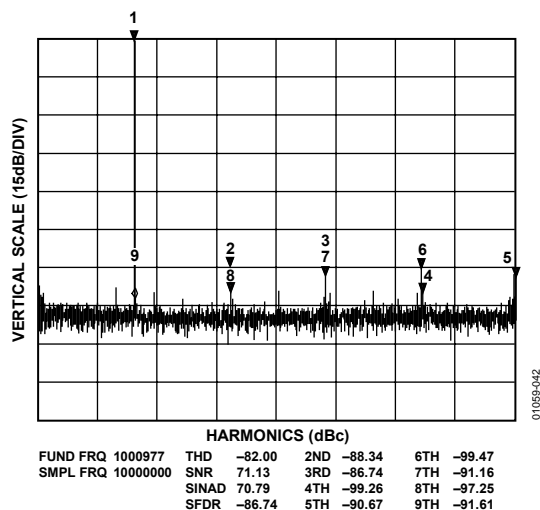


Figure 42. FFT of the AD9220 Output When Driven by the AD8042

### HDSL Line Driver

High bit rate digital subscriber line (HDSL) is a popular means of providing data communication at DS1 rates (1.544 Mbps) over moderate distances via conventional telephone twisted pair wires. In these systems, the transceiver at the customer's end is powered sometimes via the twisted pair from a power source at the central office. Sometimes, it is required to raise the dc voltage of the power source to compensate for IR drops in long lines or lines with narrow gauge wires.

Because of the IR drop, it is highly desirable to keep the power consumption of the customer's transceiver as low as possible. One means to realize significant power savings is to run the transceiver from a  $\pm 5$  V supply instead of the more conventional  $\pm 12$  V.

The high output swing and current drive capability of the AD8042 make it ideally suited to this application. Figure 43 shows a circuit for the analog portion of an HDSL transceiver using the AD8042 as the line driver.

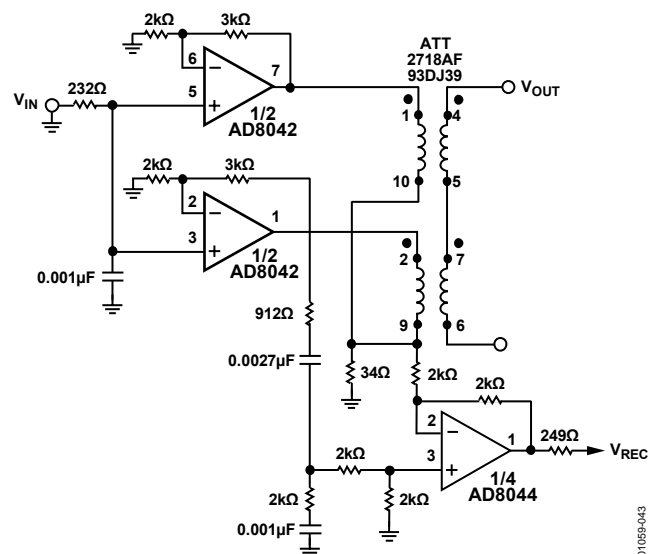


Figure 43. HDSL Line Driver

### LAYOUT CONSIDERATIONS

The specified high speed performance of the AD8042 requires careful attention to board layout and component selection. Proper RF design techniques and low-pass parasitic component selection are necessary.

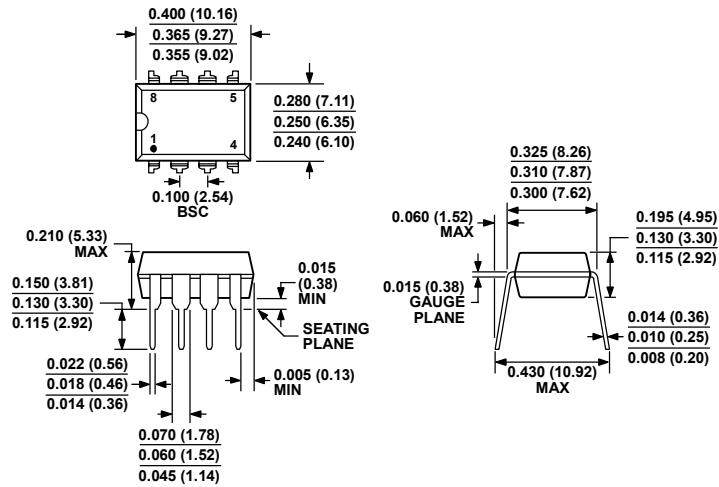
The PCB should have a ground plane covering all unused portions of the component side of the board to provide a low impedance path. The ground plane should be removed from the area near the input pins to reduce the stray capacitance.

Chip capacitors should be used for the supply bypassing. One end should be connected to the ground plane and the other within  $\frac{1}{8}$ -inch of each power pin. An additional large (0.47  $\mu$ F to 10  $\mu$ F) tantalum electrolytic capacitor should be connected in parallel, but not necessarily so close to supply current, for fast, large signal changes at the output.

The feedback resistor should be located close to the inverting input pin to keep the stray capacitance at this node to a minimum. Capacitance variations of less than 1 pF at the inverting input significantly affect high speed performance.

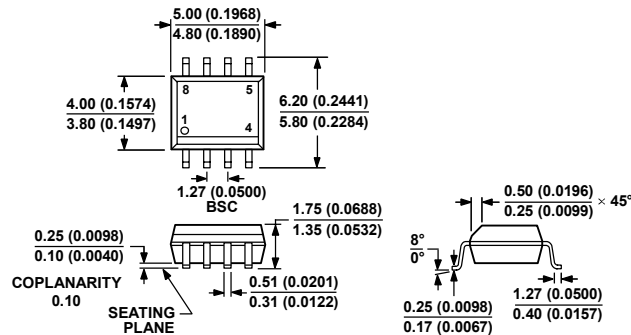
Stripline design techniques should be used for long signal traces (greater than approximately one inch). These should be designed with a characteristic impedance of 50  $\Omega$  or 75  $\Omega$  and be properly terminated at each end.

## OUTLINE DIMENSIONS



COMPLIANT TO JEDEC STANDARDS MS-001  
 CONTROLLING DIMENSIONS ARE IN INCHES; MILLIMETER DIMENSIONS  
 (IN PARENTHESES) ARE ROUNDED-OFF INCH EQUIVALENTS FOR  
 REFERENCE ONLY AND ARE NOT APPROPRIATE FOR USE IN DESIGN.  
 CORNER LEADS MAY BE CONFIGURED AS WHOLE OR HALF LEADS.

Figure 44. 8-Lead Plastic Dual In-Line Package [PDIP]  
 Narrow Body (N-8)—Dimensions shown in inches and (millimeters)



COMPLIANT TO JEDEC STANDARDS MS-012-AA  
 CONTROLLING DIMENSIONS ARE IN MILLIMETERS; INCH DIMENSIONS  
 (IN PARENTHESES) ARE ROUNDED-OFF MILLIMETER EQUIVALENTS FOR  
 REFERENCE ONLY AND ARE NOT APPROPRIATE FOR USE IN DESIGN.

Figure 45. 8-Lead Standard Small Outline Package [SOIC\_N]  
 Narrow Body (R-8)—Dimensions shown in millimeters and (inches)

## ORDERING GUIDE

Model	Temperature Range	Package Description	Package Option
AD8042AN	-40°C to +85°C	8-Lead PDIP	N-8
AD8042AR	-40°C to +85°C	8-Lead SOIC_N	R-8
AD8042AR-REEL	-40°C to +85°C	8-Lead SOIC_N, 13" Reel	R-8
AD8042AR-REEL7	-40°C to +85°C	8-Lead SOIC_N, 7" Reel	R-8
AD8042ARZ <sup>1</sup>	-40°C to +85°C	8-Lead SOIC_N	R-8
AD8042ARZ-REEL <sup>1</sup>	-40°C to +85°C	8-Lead SOIC_N, 13" Reel	R-8
AD8042ARZ-REEL7 <sup>1</sup>	-40°C to +85°C	8-Lead SOIC_N, 7" Reel	R-8
AD8042ACHIPS		DIE	

<sup>1</sup> Z = RoHS Compliant Part.



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