## 9000 series

## DISTINCTIVE FEATURES

Propotional analog output
One or two axis
Infinite resolution
Low profile design with multiple handle options

## ENVIRONMENTAL SPECIFICATIONS

－Operating Temperature：$-20^{\circ} \mathrm{C}$ to $+55^{\circ} \mathrm{C}\left(-4^{\circ} \mathrm{F}\right.$ to $\left.+131^{\circ} \mathrm{F}\right)$
－Storage Temperature：$-20^{\circ} \mathrm{C}$ to $+55^{\circ} \mathrm{C}\left(-4^{\circ} \mathrm{F}\right.$ to $\left.+131^{\circ} \mathrm{F}\right)$
－Sealing：IP65 Above panel（subject to final specifications）
－EMC Immunity Level：EN61000－4－3
－EMC Emissions Level：EN61000－6－3： 2001
－ESD：EN61000－4－2

## （4） <br> ELECTRICAL SPECIFICATIONS

－Supply Voltage： 4.75 V min to 15 V max
－Output Signal Tolerance：$\pm 10 \%$ of Output
－Supply Current：Typically 10 mA
－Output Impedance： $1.8 \Omega$
－Signal Swing：$\pm 10 \%$ of VCC to $\pm 50 \%$ of VCC
－Output at Center：$\pm 1 \%$

## MECHANICAL SPECIFICATIONS

－Mechanical Angle of Movement： $18^{\circ}$
－Mechanical Life： 10 million lifecycles
－Mass／weight： 90 g （ 0.20 lbs ）
（1．）MATERIALS
－Body：Glass Reinforced ABS
－Boot：Neoprene
－Shaft：Stainless Steel
－Other：Brass，Acetal，Nylon
The company reserves the right to change specifications without notice．


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## Proportional fingertip controllers •

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## MOUNTING

DROP IN－PANEL CUT OUT AND INSTALLATION

－The joystick is dropped into the panel cut－out． The joystick and boot must be kept in place by bezel（option $6 \& 7$ ）．
－For panel thickness of $<3 \mathrm{~mm}, \mathrm{~m} 3 \times$ 16 countersunk machine screws are recommended．
－To ensure a good panel seal，gaskets are available as an optional extra．

OPTION A－PANEL CUT OUT AND INSTALLATION

－When mounted this way the panel acts as the bezel and no separate bezel is needed．
－M3 machine screws are recommended．

OPTION B－PANEL CUT OUT AND INSTALLATION


－The joystick flange is mounted beneath the panel and the base of the boot must be brought through the panel cut－out and held in place with the circular bezel（option 4）．
－For panel thicknesses of up to 3 mm ，m3 x 16 countersunk machine screws are recommended．

## NEAR EQUIVALENT CIRCUIT



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## 5 <br> BUILD YOUR PART NUMBER



## （4）ABOUT THIS SERIES

## NOTES：

1．Bezel options：For drop in mounting，please specify bezel option 6 or 7 ．No bezel is necessary for sub－panel mounting unless the boot is required to seal to the front face of the panel－bezel option 4 ．Bezels 6 \＆ 7 clamp the boot and top face of the joystick body to the panel，whereas bezel 4 clamps only the boot．Some handles may be larger than some panel cut outs．This may restrict the choice of mounting and bezel options．Please contact APEM for assistance．
2．Springs：The 9000 series is spring return to center．The standard force requires 1.3 N （nominally）to off－center the joystick．Note：forces quoted are subject to exact joystick configuration and are provided as a guide only．
3．Dual Decode Interface：For optimum performance of the center detect signals，APEM recommends the signals are pulled high via the input resistor of typically 22 k ，on the controller circuitry．
4．Center Tap reference：All 9000 series output a center tap referece as standard．This reference is set within the joystick at $50 \%$ of VCC（ $\pm 1 \%$ ）．For optimum accuracy，the outputs should be read relative to the center tap．
5．Non－standard：Further non－standard options including custom handles or special limiter plates are available．Please contact APEM for further details．

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## DIMENSIONS



## HANDLE OPTIONS





Aluminum
Anodized
Black
Upon Request
Uses APEM IA Switches


Aluminum
Anodized
Black
Not Available
Uses APEM IA Switches


MATERIAL
FINISH
STANDARD COLOR
OTHER COLORS
NOTES：

Nylon
Sparked Matt
Black
Upon Request


ABS
Sparked Matt
Black
Upon Request
Uses APEM IA Switches


Nylon
MATERIAL
FINISH
STANDARD COLOR OTHER COLORS NOTES：


Aluminum
Anodized
Black
Not Available


Delrin
Gloss
Black
Not Available
Uses APEM IS Switches

NOTES：
1．Dimensions are in mm ／（inch）．
2．Unless otherwise specified，all joysticks are supplied with black switches in the handles．

## －•• CONFIGURATION OPTION <br> CIRCUITRY

The 9000 series joystick operates by passing an oscillating current through a drive coil，directly mounted at the lower end of the operating lever，and immediately above the four sensing coils．When the shaft and drive coil moves away from the center，the signals detected in each opposing pair of coils increase nominally in proportion to deflection．

The phase of those signals determine the direction．Synchro－ nous electronic switches followed by integrating amplifiers provide DC signals directly equivalent to those of potentio－ meter joysticks，but with fixed output impedance and free of wiper noise and track wear．

DUAL DECODE
Designed for use in the most safety－critical applications，the 9000 series incorporates comprehensive internal monitoring circuitry whereby output signals are continually compared with separately generated＇mirror signals＇．In the unlikely event of an internal fault，the dual decode system will gene－ rate a separate fault signal，enabling the controller to fail－to－ safe．The dual decode system is a complete internal self－mo－ nitoring system，providing a far higher standard of protection．

An additional，＇away from center＇signal is also available whe－ never required．Although the monitoring of the joystick is fully internal，the inverse＇mirror signals＇can be available as external outputs where the monitor function is incorporated within the controller circuitry．

GUIDED FEEL
The 9000 series may also be specified with guided feel． A joystick with guided feel moves more readily towards the poles（ $N, S, E$ and $W$ ）and while it can still move away from the poles，the force required to do so is grea－ ter．Unless specified otherwise，joysticks are supplied as standard without guiding．This standard configuration allows the user to move the joystick anywhere within the limiter with the same force and without any bias．

FUNCTIONAL OPTIONS
The 9000 series can be configured in three different modes：
－Orthoganol，standard signals－Replicating that of a potentiometer．
－Deliberate signal mixing－Ideal for those applications whereby the method of steering is by controlling two motors．For example one motor uses $X+Y$ signals and the other uses $X-Y$ signals．This mixing is achieved by internally orientating the signals at $45^{\circ}$ to normal． Typical applications may be twin propeller boats， tracked vehicles，or wheelchairs．
－Deliberate signal interaction－Enables reduction in one signal as the other increases．This option is particularly beneficial where it is undesirable to maintain full forward speed while turning and vice versa．

